



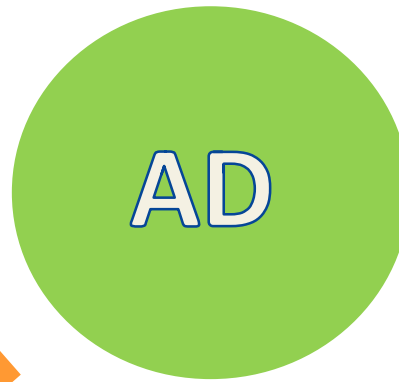
Automatische Fahrzeuge (SAE Level 5)

Auswirkungen auf
Gesellschaft, Sicherheit
Mobilität und Technologie

R. Pfliegl, 2. Februar 2017



Utopie oder Realität?



ist es eine...

...technische/ technologische
Herausforderung?

...eine gesellschaftliche
Zielsetzung...oder

JUST 4 FUN ?



WEDER.....NOCH !

Agenda



- Einleitung
- Hauptprobleme
- Steuerung des Verkehrs
- Schlüsseltechnologien
- Europäische Initiativen und Projekte
- Roadmaps
- Zusammenfassung

Wachstum



White Book of European Commission 2010:

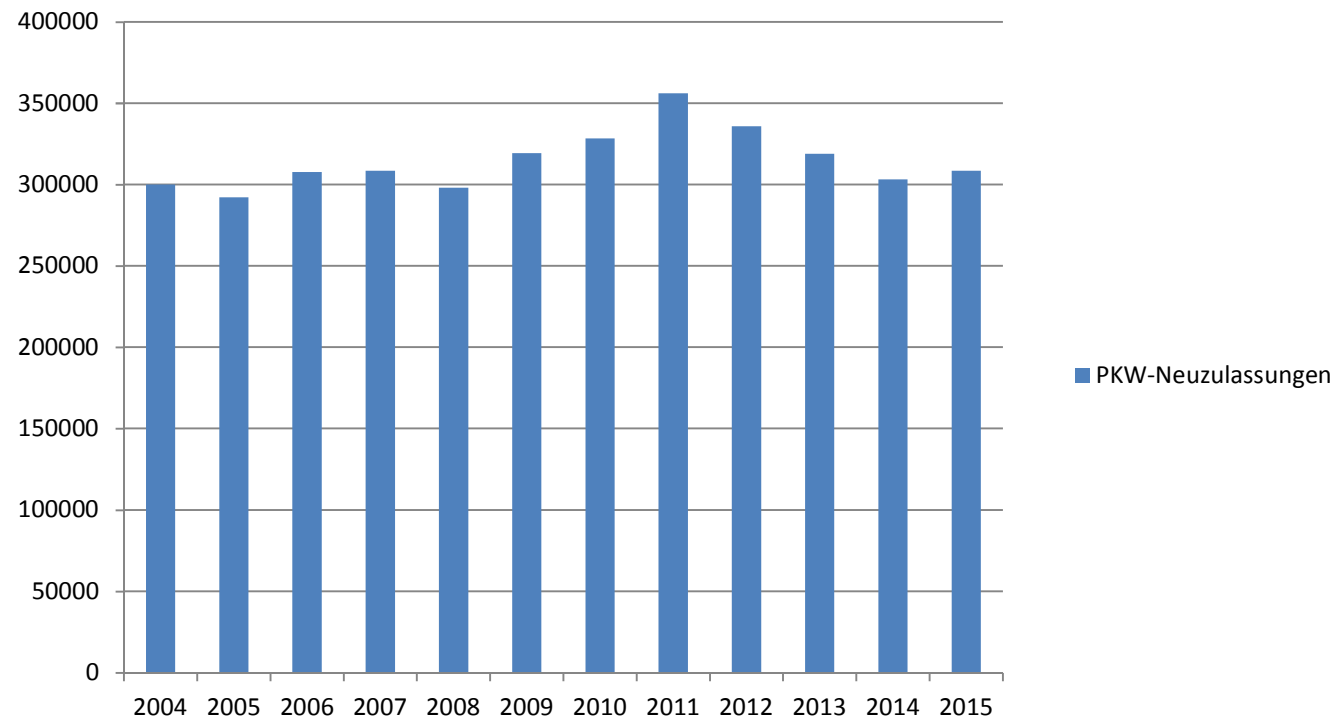
+50% Truck transport till 2025

+30% Passenger cars till 2025

-25% CO2 emission till 2030

-80% CO2 emission till 2050

PKW-Neuzulassungen in Österreich

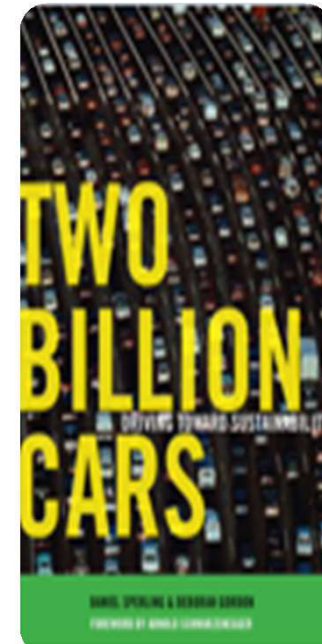
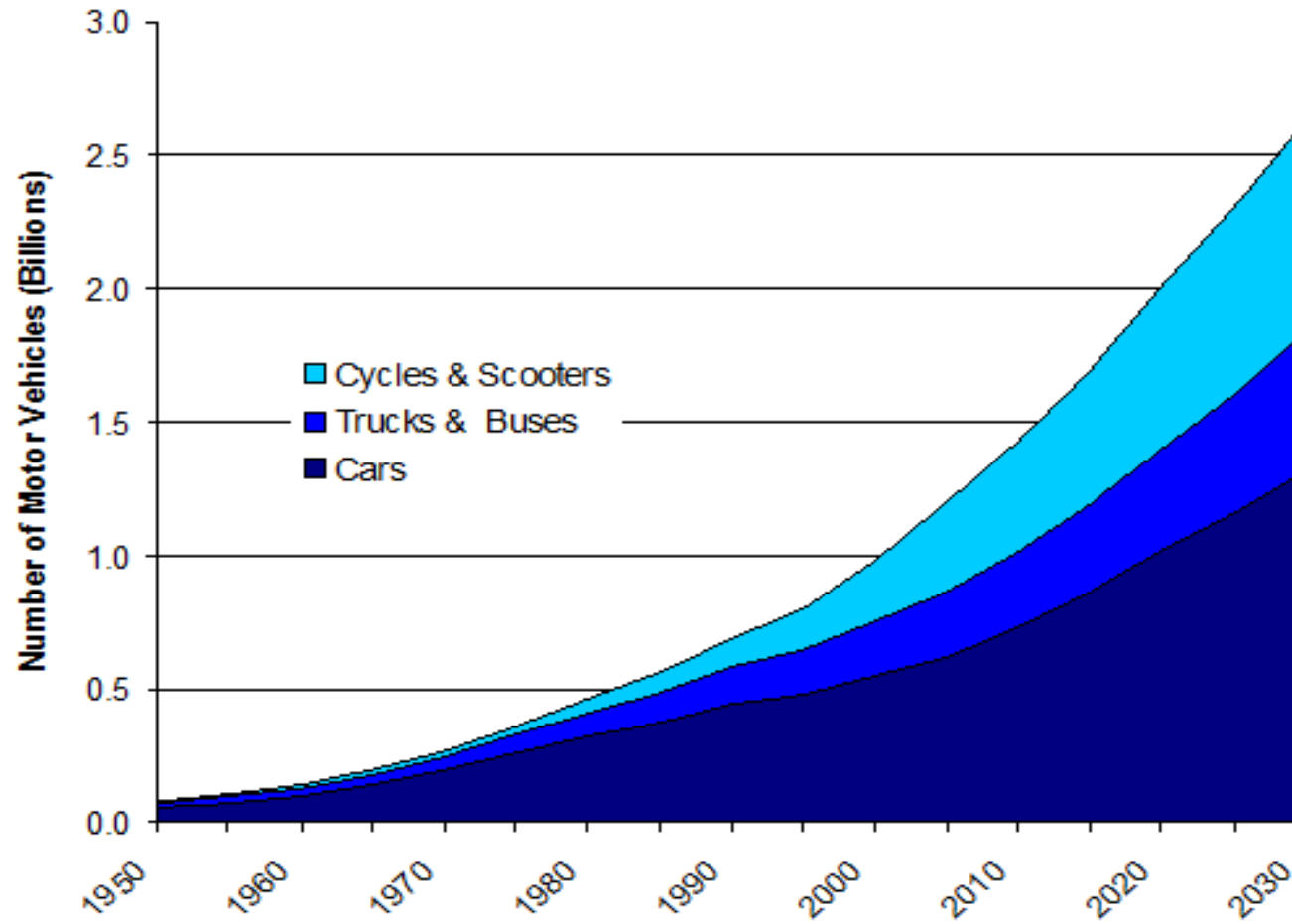




Zulassungen in Österreich gesamt

PKW	4753812
Motorräder	762647
LKW	428017
Busse	9755
Sonstige (inkl. Anhänger)	1342044
Gesamtzulassungen	7295275

2 Milliarden Fahrzeuge Global 2020





- Das fördert einerseits die ‚Accessibility‘..... also die Möglichkeit Zugang zu **Beschäftigung** und **Freizeitbetätigung** zu gewährleisten
- Ist aber andererseits verbunden mit zahlreichen Problembereichen.....

Verkehrssicherheit I



Verkehrssicherheit II



Volkswirtschaftliche Unfallkosten mit Personenschaden pro Kopf

Volkswirtschaftliche Unfallkosten [Angaben in Euro]

Anteil der Kosten für ...	alle Straßen	Autobahn	Schnellstraße
Getötete pro durchschnittlichem Unfall mit Personenschaden (UPS)	44.905	91.854	140.288
Schwerverletzte pro durchschnittlichem UPS	114.044	132.107	140.704
Leichtverletzte pro durchschnittlichem UPS	26.430	31.437	27.232
Sachschaden pro durchschnittlichem UPS	5.245	5.245	5.245
Summe Kosten pro durchschnittlichem UPS	190.625	260.644	313.469

Gesamte volkswirtschaftliche Unfallkosten mit Personenschaden



volkswirtschaftliche Unfallkosten der UPS im Jahr 2011 (inklusive des menschlichen Leids)
 [Angaben in Euro]

	Anzahl	durchschnittliche Unfallkosten	Unfallkosten 2011
Getötete	523	3.016.194	1.577.469.462
Schwerverletzte (inklusive 90% der Verletzten nicht erkennbaren Grades)	10.502	381.480	4.006.302.960
Leichtverletzte (inklusive 10% der Verletzten nicht erkennbaren Grades)	34.522	26.894	928.434.668
Sachschaden (pro UPS)	35.129	5.245	184.251.605
Summe			6.696.458.695



Effiziente Verkehrsabwicklung?

Effizienz I



Effizienz II



Effizienz III



Limitiertes Platzangebot der Verkehrsinfrastruktur



Mögliche Antworten



- Zugangsbeschränkungen

oder

- Bessere Koordination der Nutzung der Infrastruktur (**räumlich** und **zeitlich**) !

Wer übernimmt die Verantwortung / Initiative

- Bundesregierung?
- Örtlichen Behörden?
- Infrastrukturbetreiber?
- Kapazitätsmanager?
- Jeder einzelne Benutzer?



=> **Von Oben nach Unten oder umgekehrt ??**

Motivation



	1	Road Safety: Vision Zero	Road safety improvements by reducing human driving errors → 90% of all accidents are caused by human errors	
	2	Traffic Management	- Optimization of traffic flow management - Convenient, time efficient driving via automation → 80% improvement in traffic throughput	
	3	Reducing Emissions	Reduction of fuel consumption & CO ² emission (through optimization of traffic flow management) → 23 to 39% improvement in highway fuel economy	
	4	Demographic Change	- Support unconfident drivers - Enhance mobility for elderly people → Allow a variety of age ranges to be mobile	
	5	Innovation High technology	- New economic paradigm – supporting innovation policies of regions - Competitiveness / high skill employment → 56 minutes per day freed up for other uses (US)	

0-100+!

Social equality!

[Source: Tech.AD, Conference on Automated Driving, Berlin, 2015]



Paradigmenwechsel

vom

Konventionellen Verkehrsmanagement auf den
verschiedenen Verkehrsträgern

zum

Integrierten Infrastruktur Kapazitätsmanagement

Verkehrssteuerung



Inland navigation
Sea navigation

Traffic control



Individual Traffic



Rail



Air

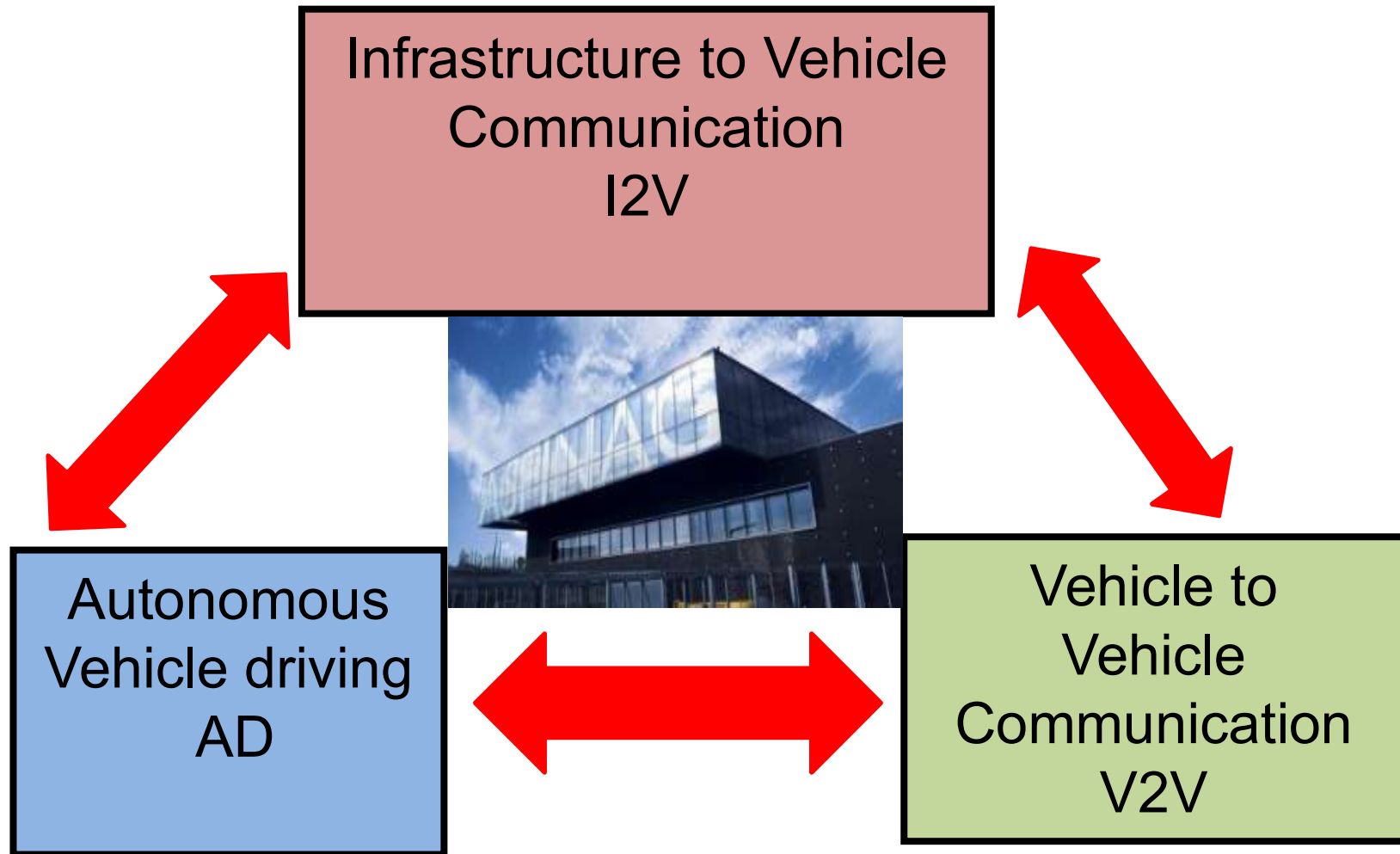
distributed

central

Kernelemente – Integriertes Verkehrsmanagement



3 Säulen der zukünftigen Verkehrssteuerung



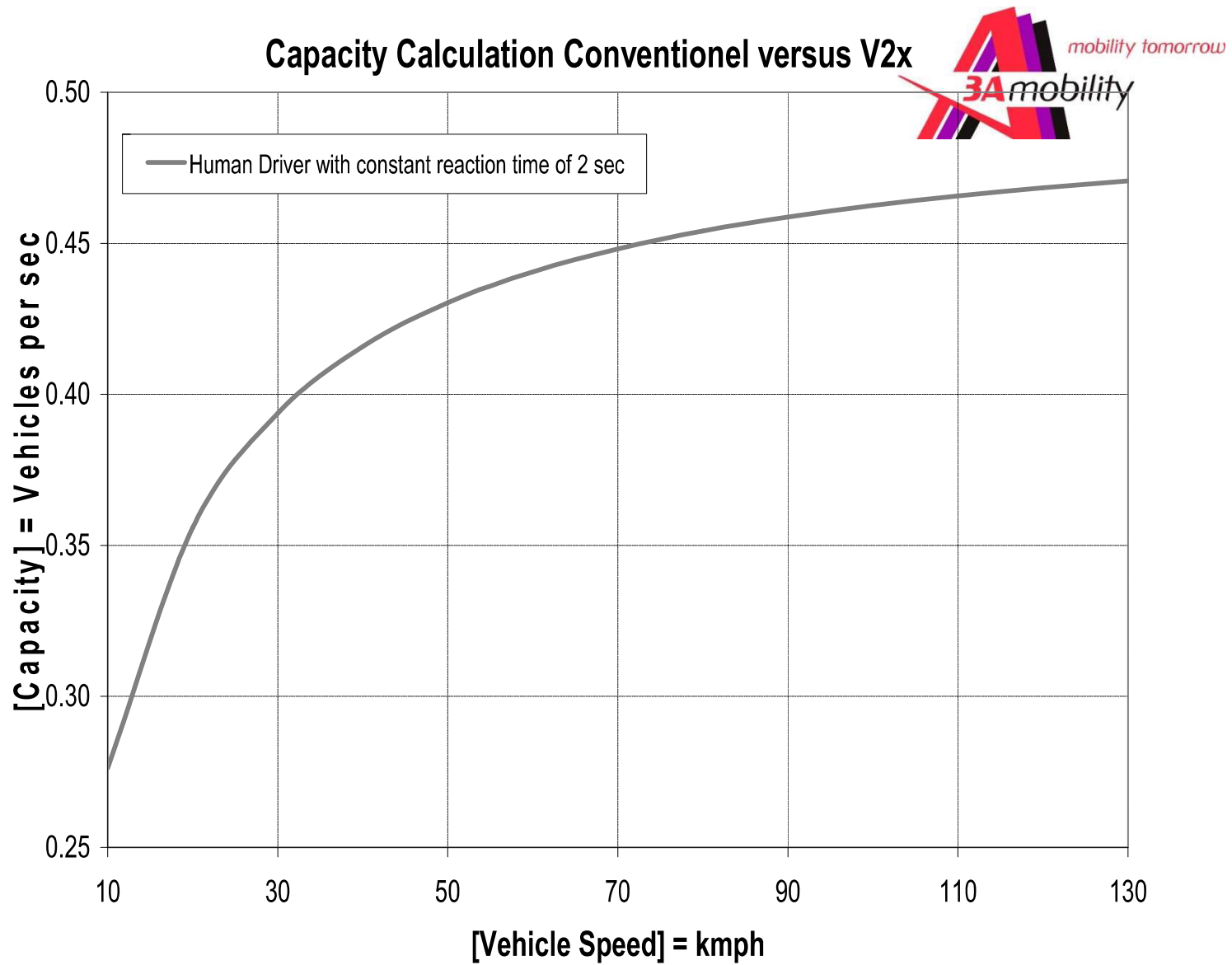


Nutzen wir heute die verfügbare
Infrastrukturkapazität effizient aus???

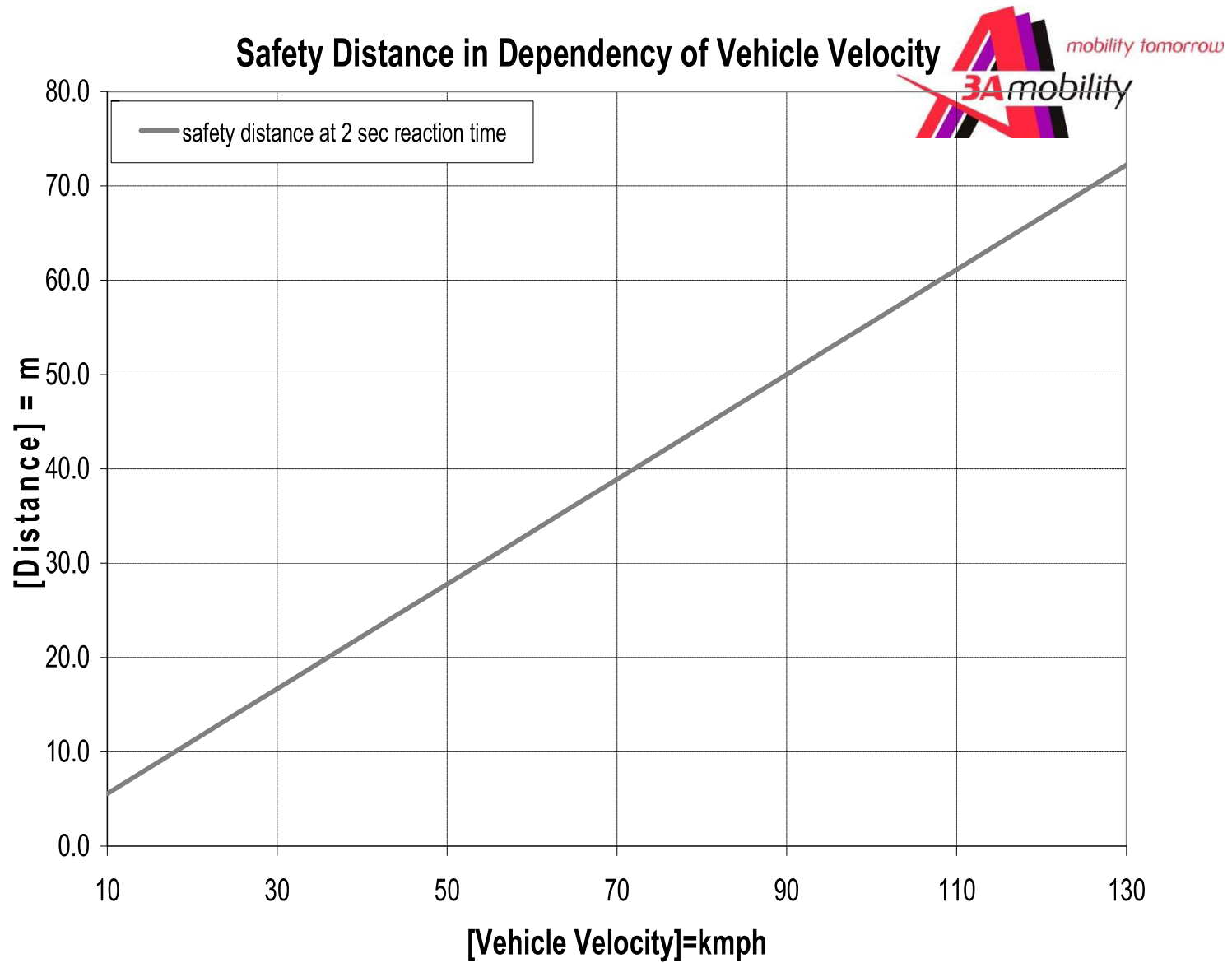


- Wie ist der Abstand aufeinanderfolgender Fahrzeuge (z.B. PkW) gegenwärtig gesetzlich geregelt????

Kapazitätsberechnung I



Kapazitätsberechnung II



Kapazitätsberechnung III

Capacity Calculation Conventional versus V2x



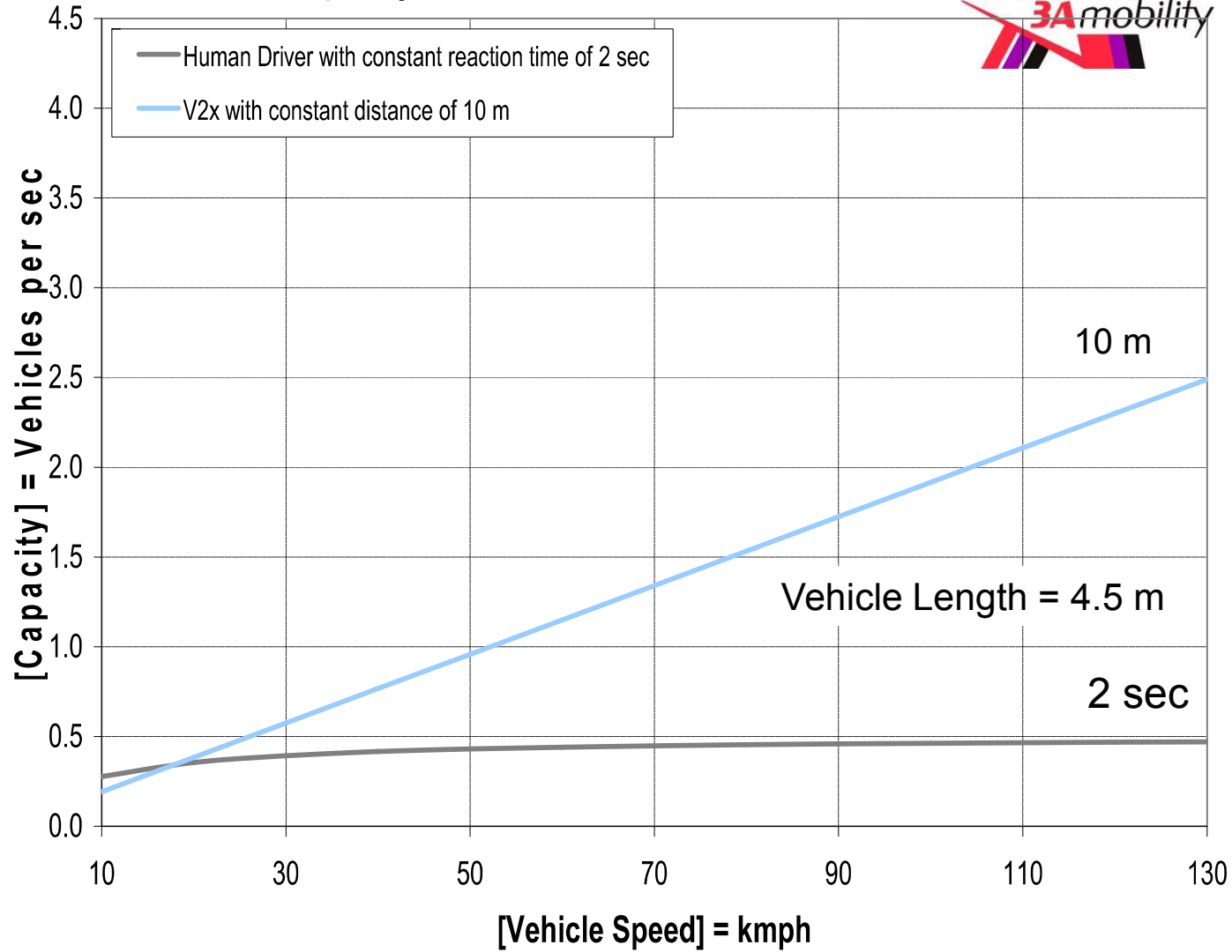
Kapazitätsberechnung III

Capacity Calculation Conventional versus V2x



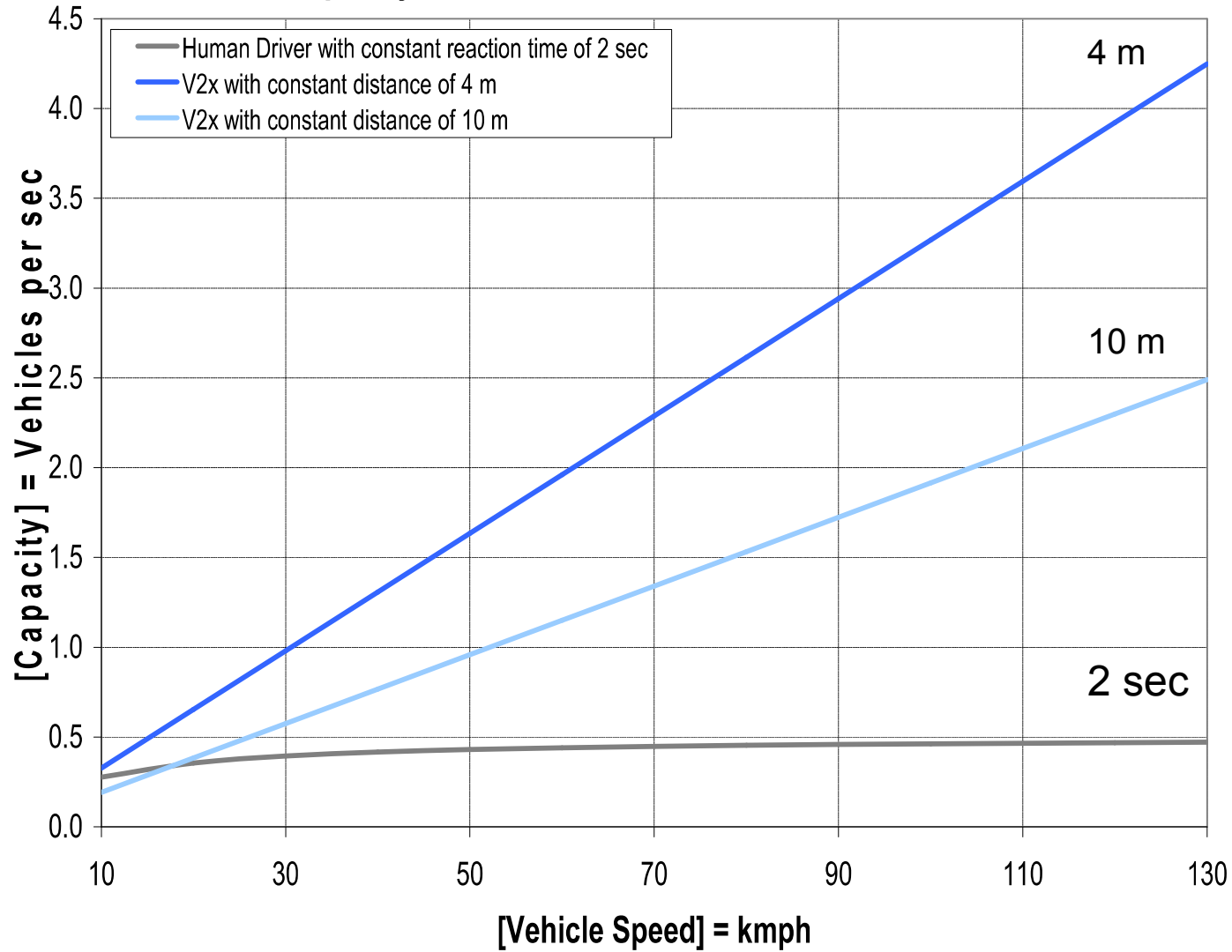
Kapazitätsberechnung IV

Capacity Calculation Conventional versus V2x



Kapazitätsberechnung VI

Capacity Calculation Conventional versus V2x





Schlüsseltechnologien für Automatische Fahrzeuge



Begriffsdefinition

Autonome Fahrzeuge (DARPA Challenge):

Das Fahrzeug erhält einen Zielpunkt (z.B. GPS Koordinaten) und hat ohne jegliche Einflussnahme den Weg zum Zielpunkt zu finden)

Automatische Fahrzeuge:

Das Fahrzeug folgt mittels eines Navigationssystems einen vorgegebenen Weg bis zum Ziel

SAE – Roadmap



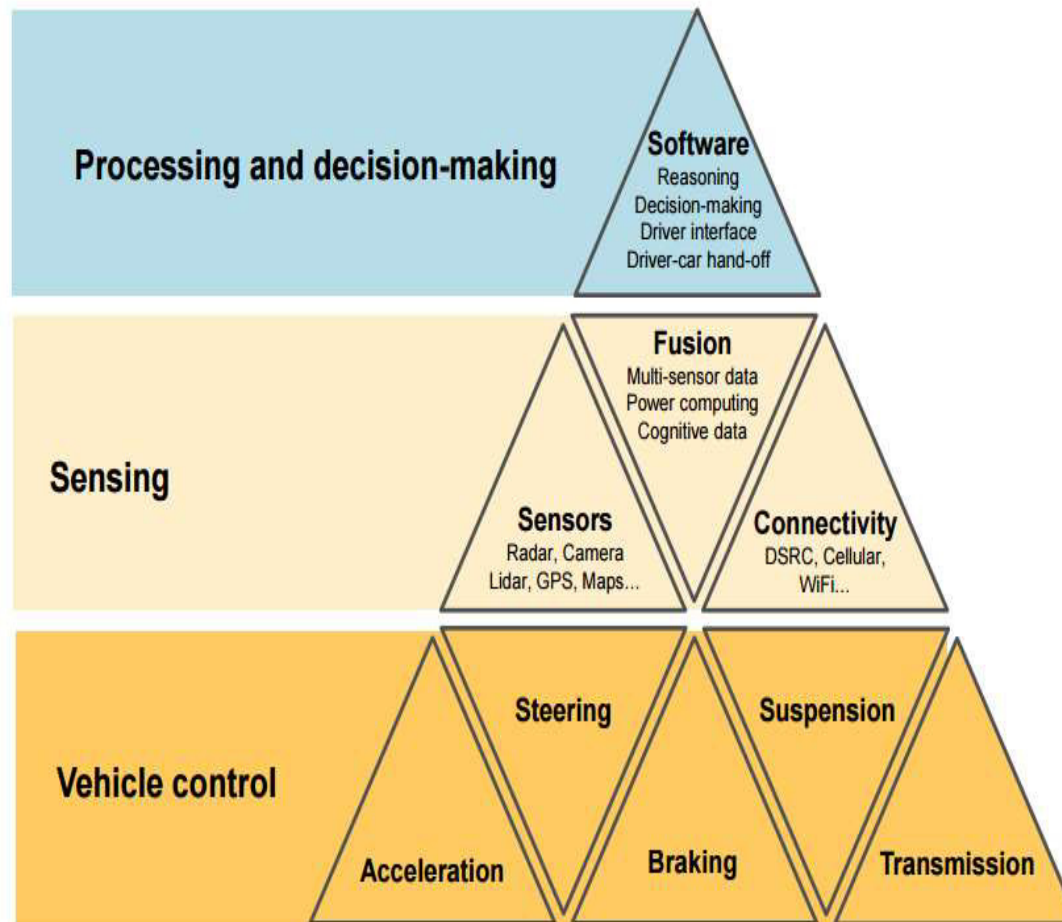
Summary of Levels of Driving Automation for On-Road Vehicles

This table summarizes SAE International’s levels of *driving* automation for on-road vehicles. Information Report J3016 provides full definitions for these levels and for the italicized terms used therein. The levels are descriptive rather than normative and technical rather than legal. Elements indicate minimum rather than maximum capabilities for each level. “System” refers to the driver assistance system, combination of driver assistance systems, or *automated driving system*, as appropriate.

The table also shows how SAE’s levels definitively correspond to those developed by the Germany Federal Highway Research Institute (BAST) and approximately correspond to those described by the US National Highway Traffic Safety Administration (NHTSA) in its “Preliminary Statement of Policy Concerning Automated Vehicles” of May 30, 2013.

Level	Name	Narrative definition	Execution of steering and acceleration/ deceleration	Monitoring of driving environment	Fallback performance of <i>dynamic driving task</i>	System capability (<i>driving modes</i>)	BAST level	NHTSA level
<i>Human driver monitors the driving environment</i>								
0	No Automation	the full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems	Human driver	Human driver	Human driver	n/a	Driver only	0
1	Driver Assistance	the <i>driving mode</i> -specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i>	Human driver and system	Human driver	Human driver	Some driving modes	Assisted	1
2	Partial Automation	the <i>driving mode</i> -specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i>	System	Human driver	Human driver	Some driving modes	Partially automated	2
<i>Automated driving system (“system”) monitors the driving environment</i>								
3	Conditional Automation	the <i>driving mode</i> -specific performance by an <i>automated driving system</i> of all aspects of the <i>dynamic driving task</i> with the expectation that the <i>human driver</i> will respond appropriately to a <i>request to intervene</i>	System	System	Human driver	Some driving modes	Highly automated	3
4	High Automation	the <i>driving mode</i> -specific performance by an <i>automated driving system</i> of all aspects of the <i>dynamic driving task</i> , even if a <i>human driver</i> does not respond appropriately to a <i>request to intervene</i>	System	System	System	Some driving modes	Fully automated	3/4
5	Full Automation	the full-time performance by an <i>automated driving system</i> of all aspects of the <i>dynamic driving task</i> under all roadway and environmental conditions that can be managed by a <i>human driver</i>	System	System	System	All driving modes	.	

Building Blocks of Automated Driving



Key Technologies I



- Autonomous Vehicle Functions (driving)
- V2X communication
- Mass Data Processing (simulation, forecast, capacity calculation, etc.)
- Traveller Services Pre-trip/ on-Trip (information, planning, booking, real time notification, individualized services,..)

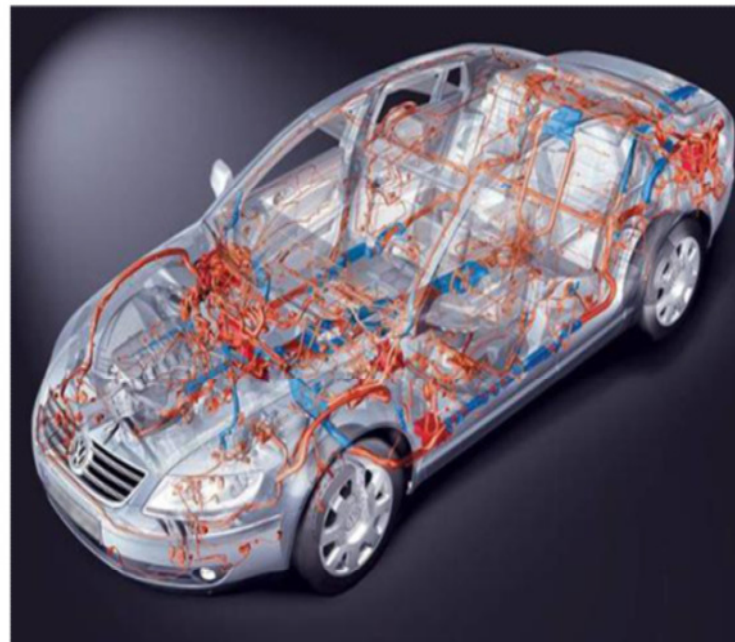
Key Technologies II



Satellite Cellular WiFi Radio DSRC

Blue Tooth
& RF

Wireless
Sensors



CD & MP3

Mechanics'
Diagnostic
Tools

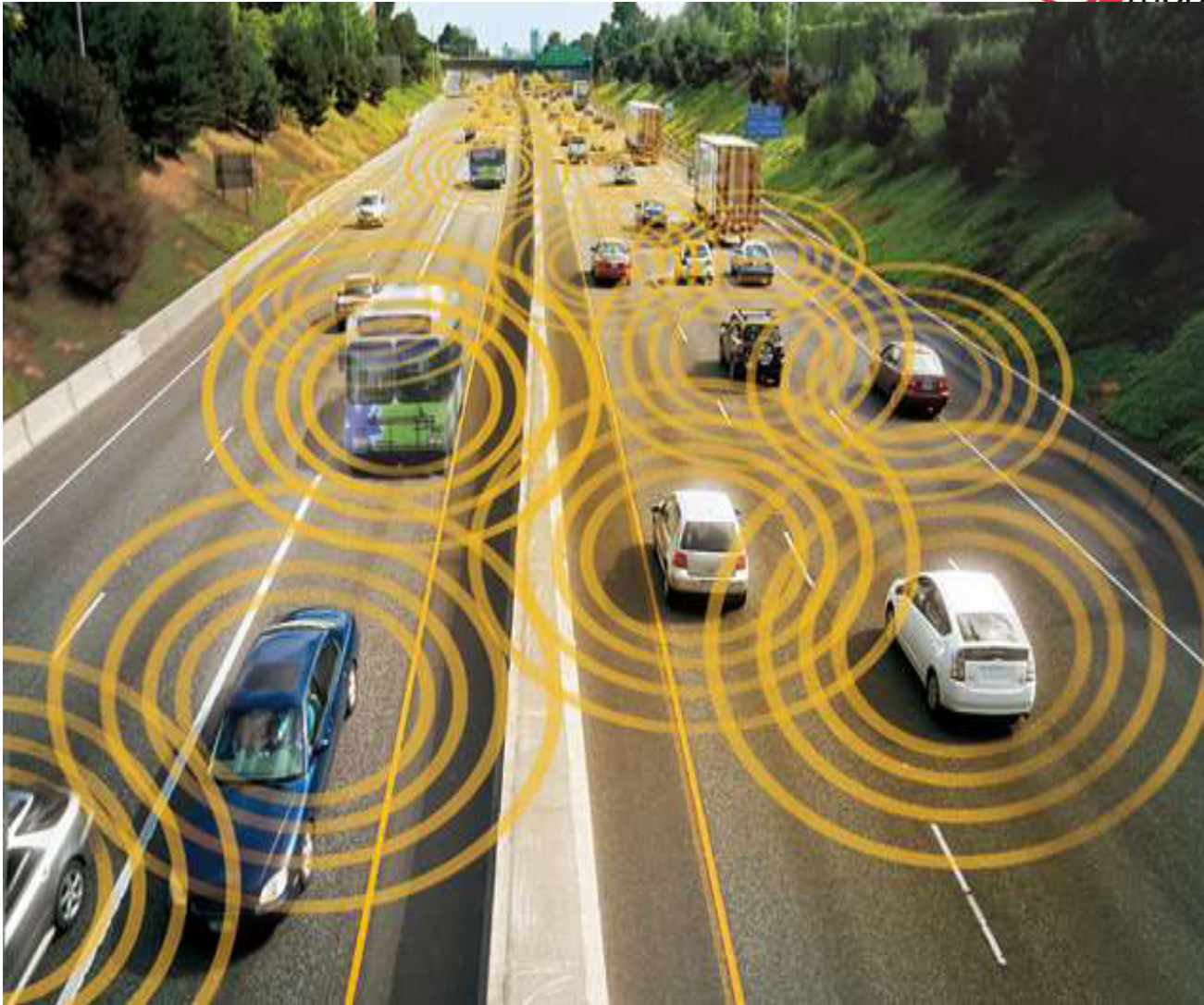
Key Technologies III

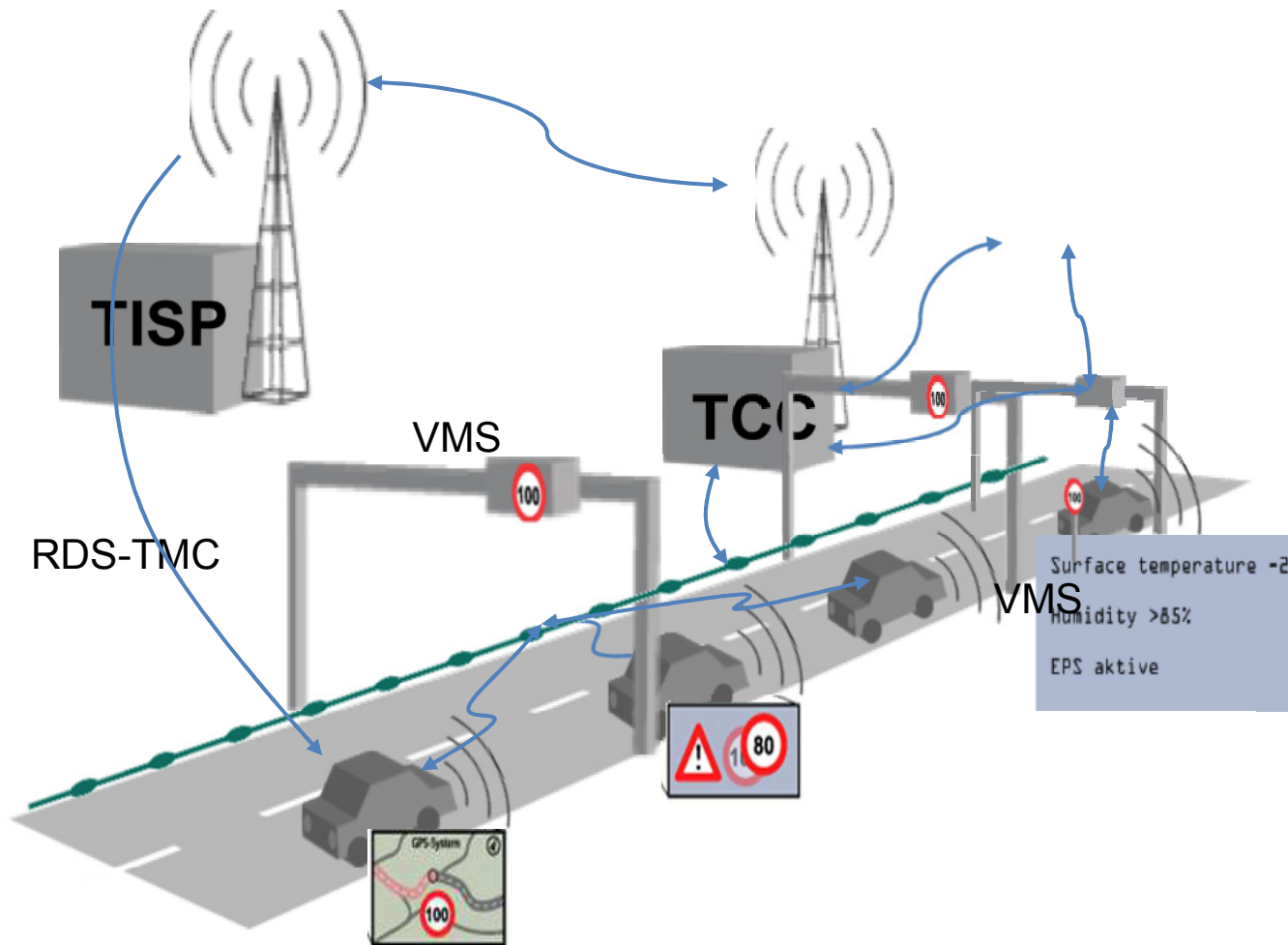


Umsetzung

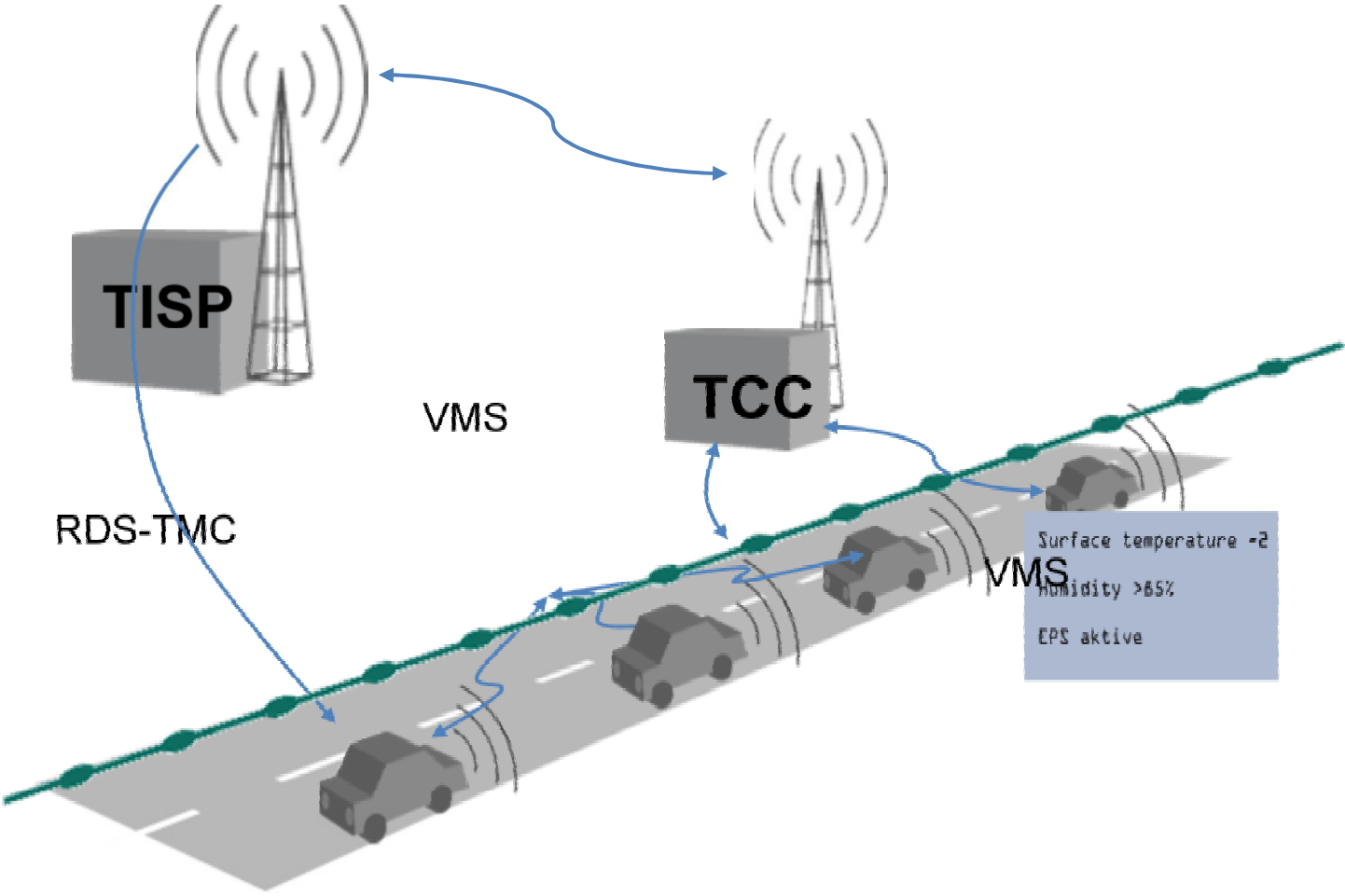


V2V





V2I



V2X



- Wie findet das automatische Fahrzeug den Weg von A nach B????
- Reichen die Funktionen und Technologien aus die wir bis jetzt besprochen haben???

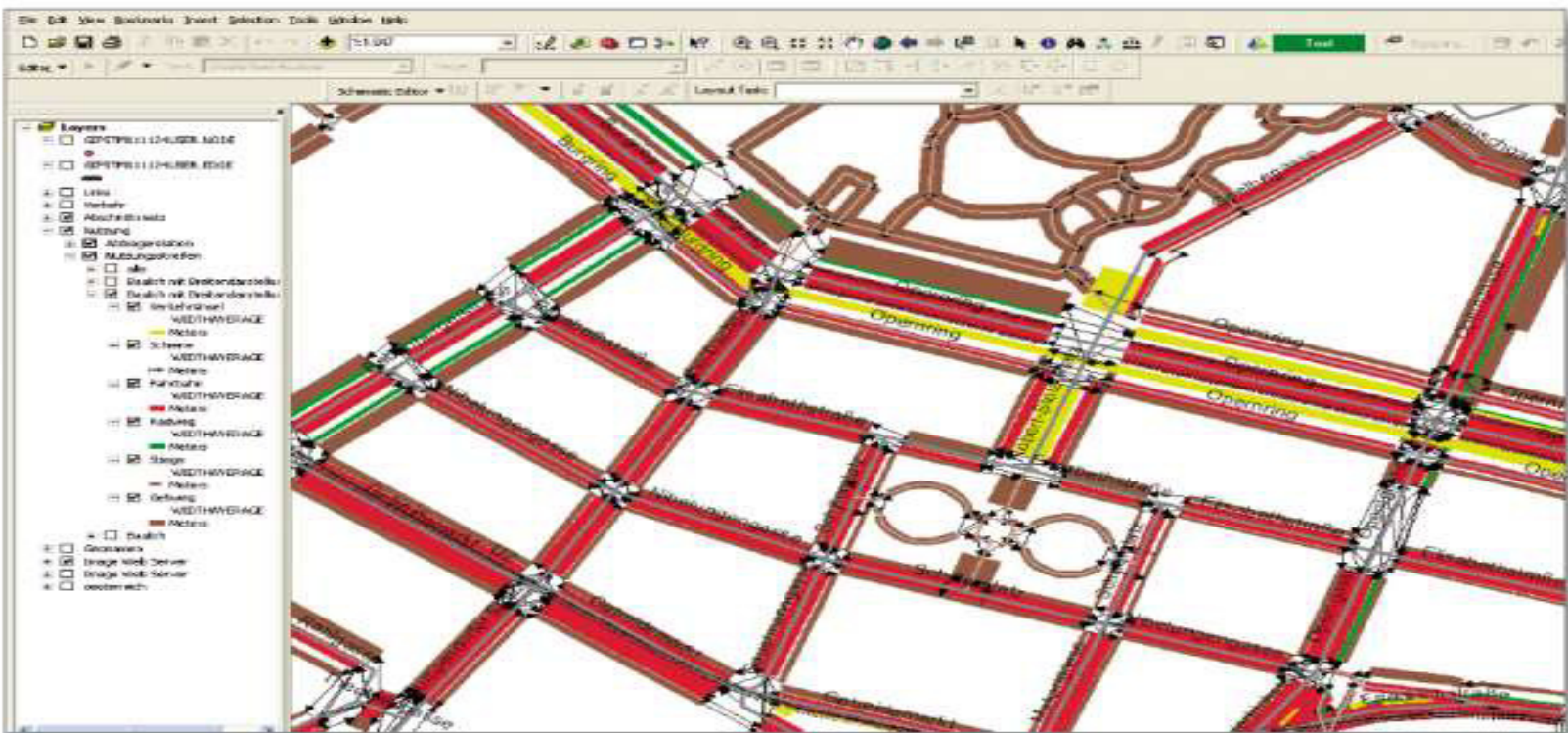
Navigationssystem



GIP.gv.at (Graph Integration Platform)

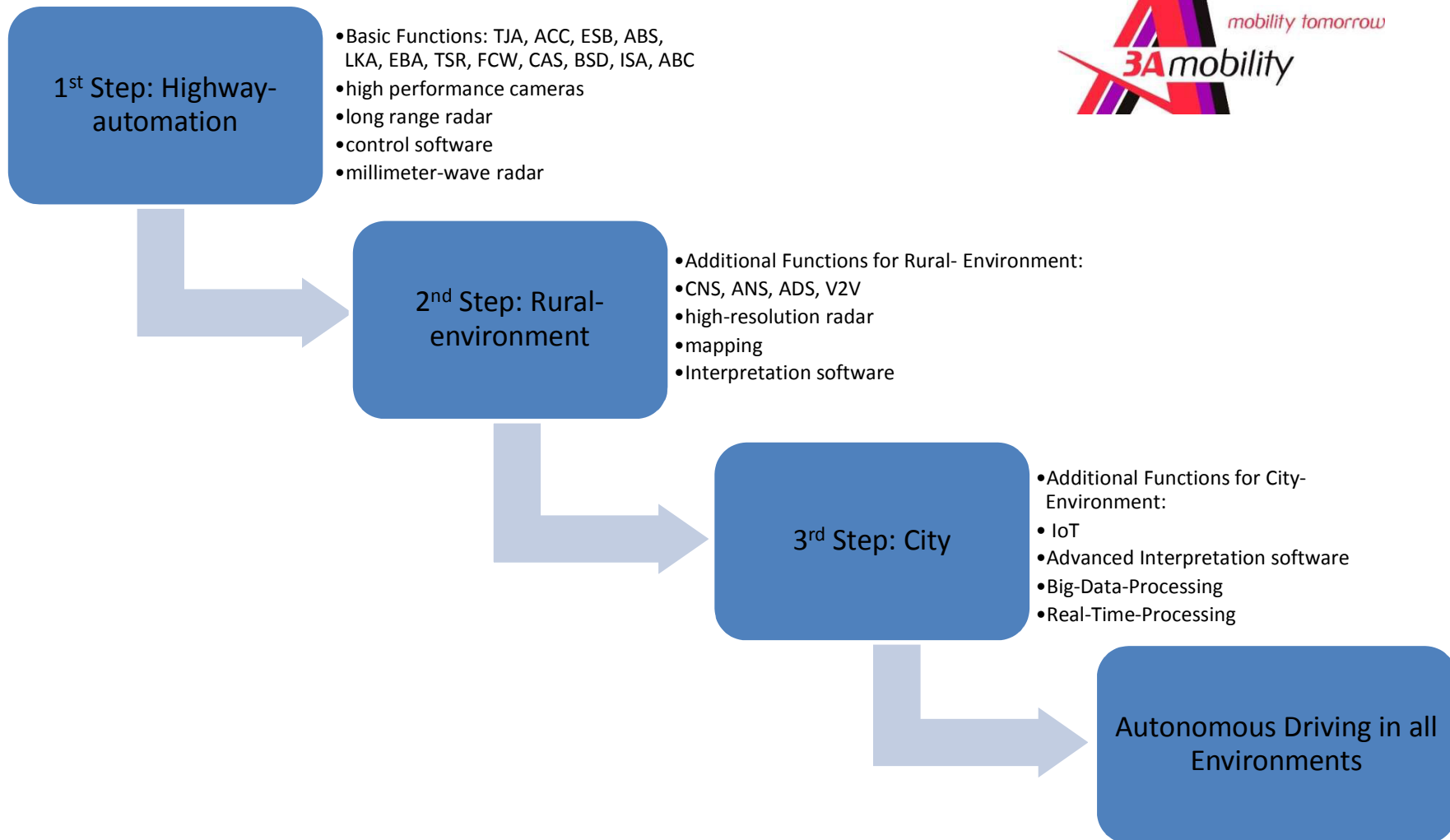


- Integriertes Informationssystem für die Vehicleführung basierend auf einem gemeinsamen Graph, e.g. GIP
- Für alle Verkehrsanforderungen:
 - Regional und Urban Transport Planning
 - e-Government Processes, Regulations, Notifications
 - Guidance , Logistics
 - Operations, Control and
 - Monitoring and Quality Assessment





Stufenweise Einführung

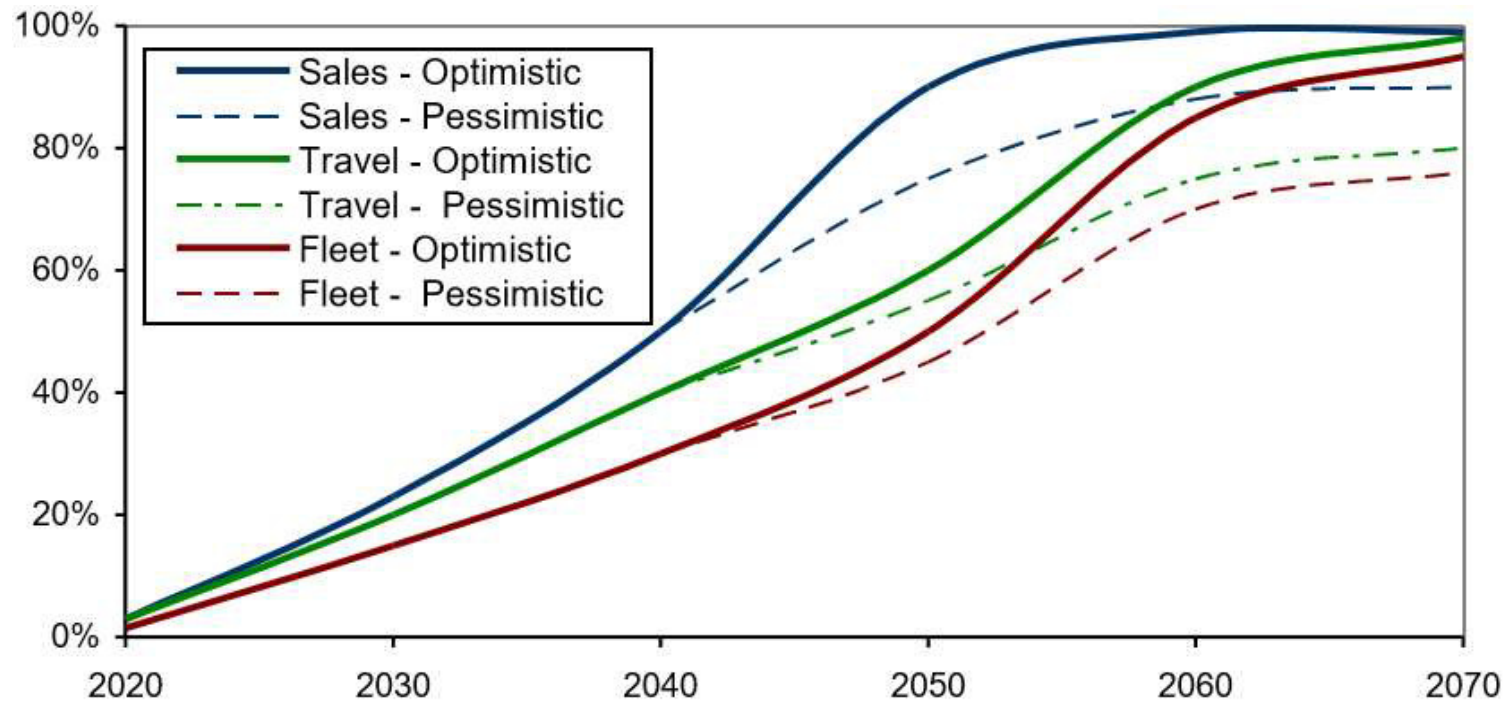


Autonomous Vehicle Sales, Fleet and Travel Projections (Based on Table)

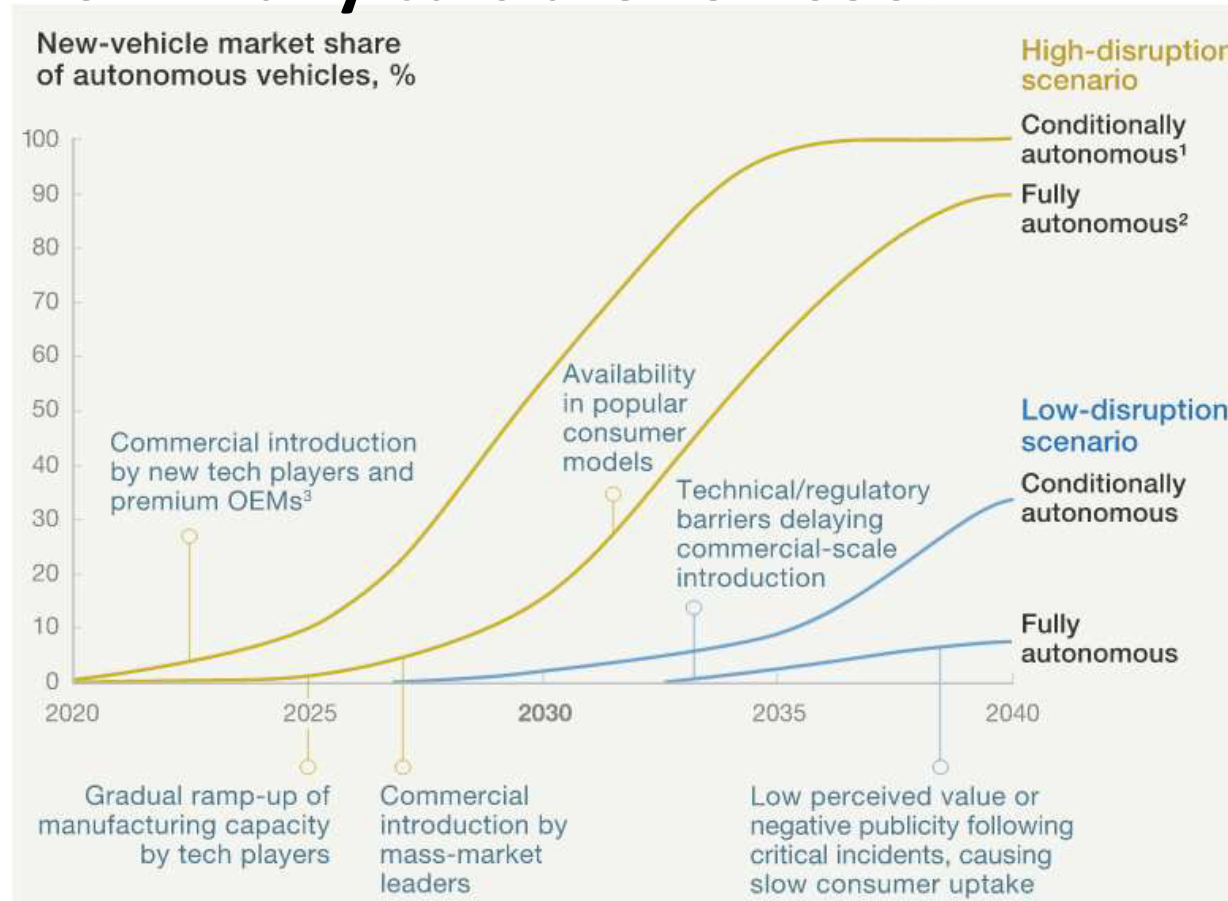


Name	Deployment Cycle	Typical Cost Premium	Market Saturation Share
Air bags	25 years (1973-98)	A few hundred dollars	100%, due to federal mandate
Automatic transmissions	50 years (1940s-90s)	\$1,500	90% U.S., 50% worldwide
Navigation systems	30+ years (1985-2015+)	\$500 and rapidly declining	Uncertain; probably over 80%.
Optional GPS services	15 years	\$250 annual	2-5%
Hybrid vehicles	25+ years (1990s-2015+)	\$5,000	Uncertain. Currently about 4%.

Vehicle Technology Deployment Summary



How many cars are L5 2030?



Factors in disruption scenarios

Regulatory challenges
 Safe, reliable technical solutions
 Consumer acceptance, willingness to pay

High disruption

Fast
 Comprehensive
 Enthusiastic

Low disruption

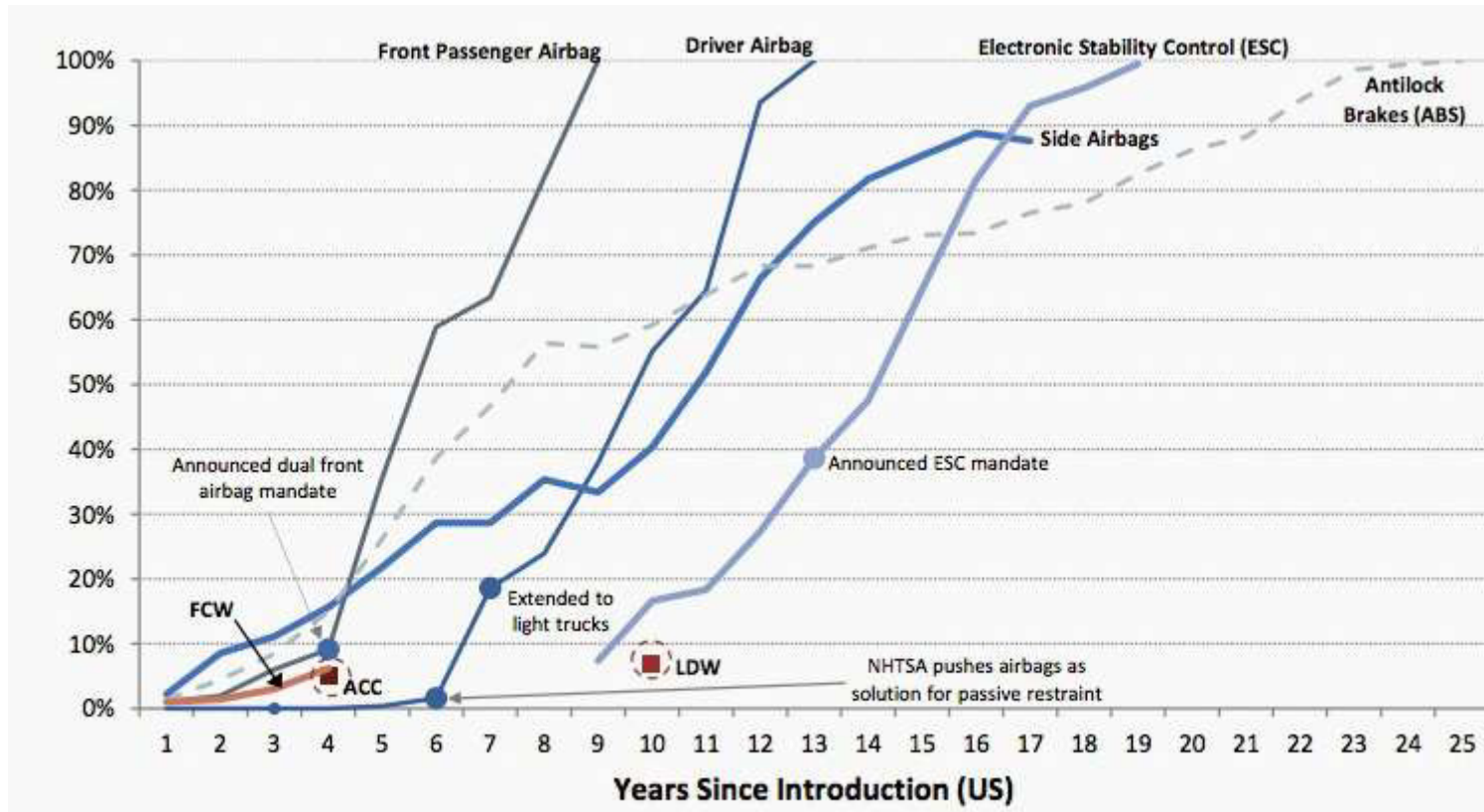
Gradual
 Incomplete
 Limited

¹Conditionally autonomous car: the driver may take occasional control.

²Fully autonomous car: the vehicle is in full control.

³Original-equipment manufacturers.

Penetration of select safety features in US



Source: Wards, IHS, NHTSA, RBC Capital Markets estimates

**The new EU Framework
Programme
for Research and Innovation,
2014-2020
Instrument for consistent
development**

The new EU Framework Programme for Research and Innovation, 2014-2020

- ➔ **A budget of € 77 billion for 7 years**
- ➔ **A core part of Europe 2020, Innovation Union and the European Research Area:**
 - **Responding to the economic crisis** to invest in future jobs and growth
 - **Addressing people's concerns** about their livelihoods, safety and environment
 - **Strengthening the EU's global position** in research, innovation and technology

Eco-Mobility 2025^{plus}

Roadmap



ERTRAC – Roadmap

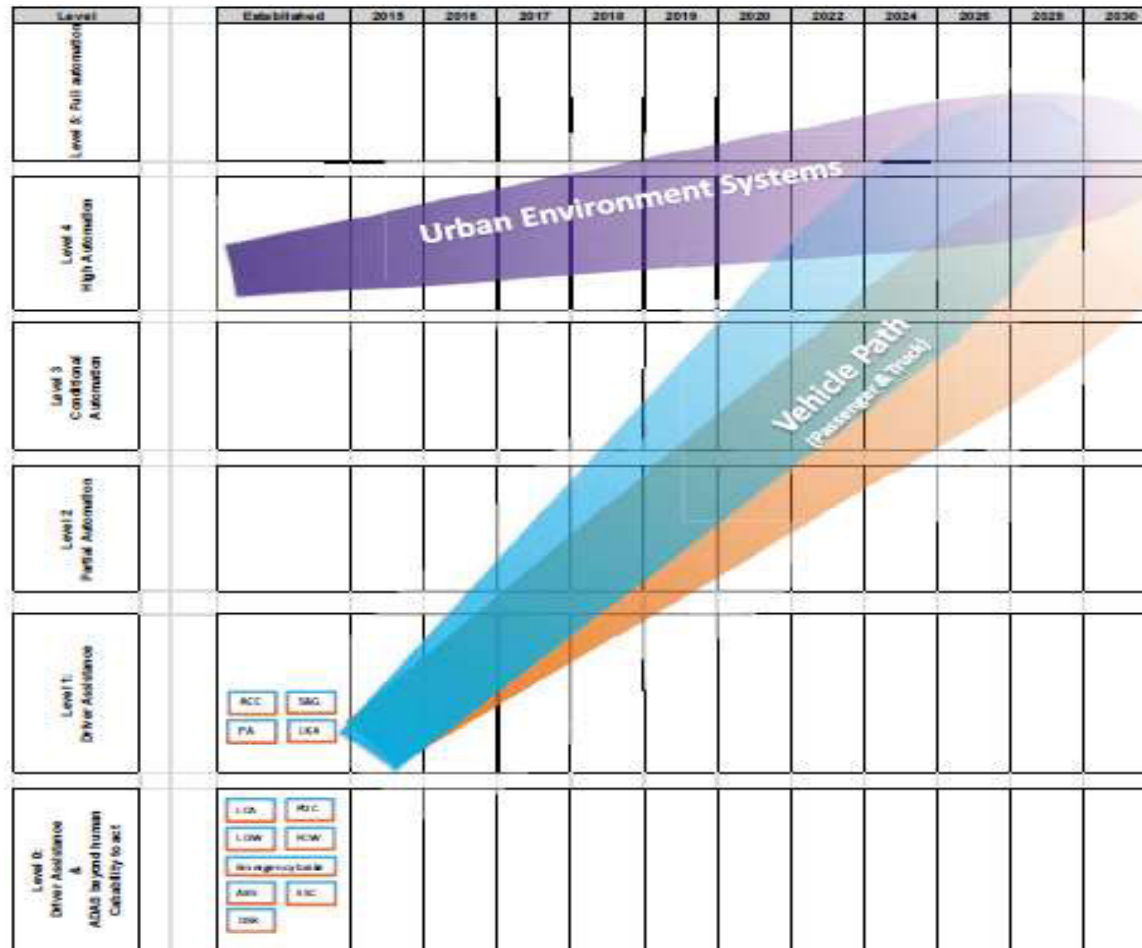
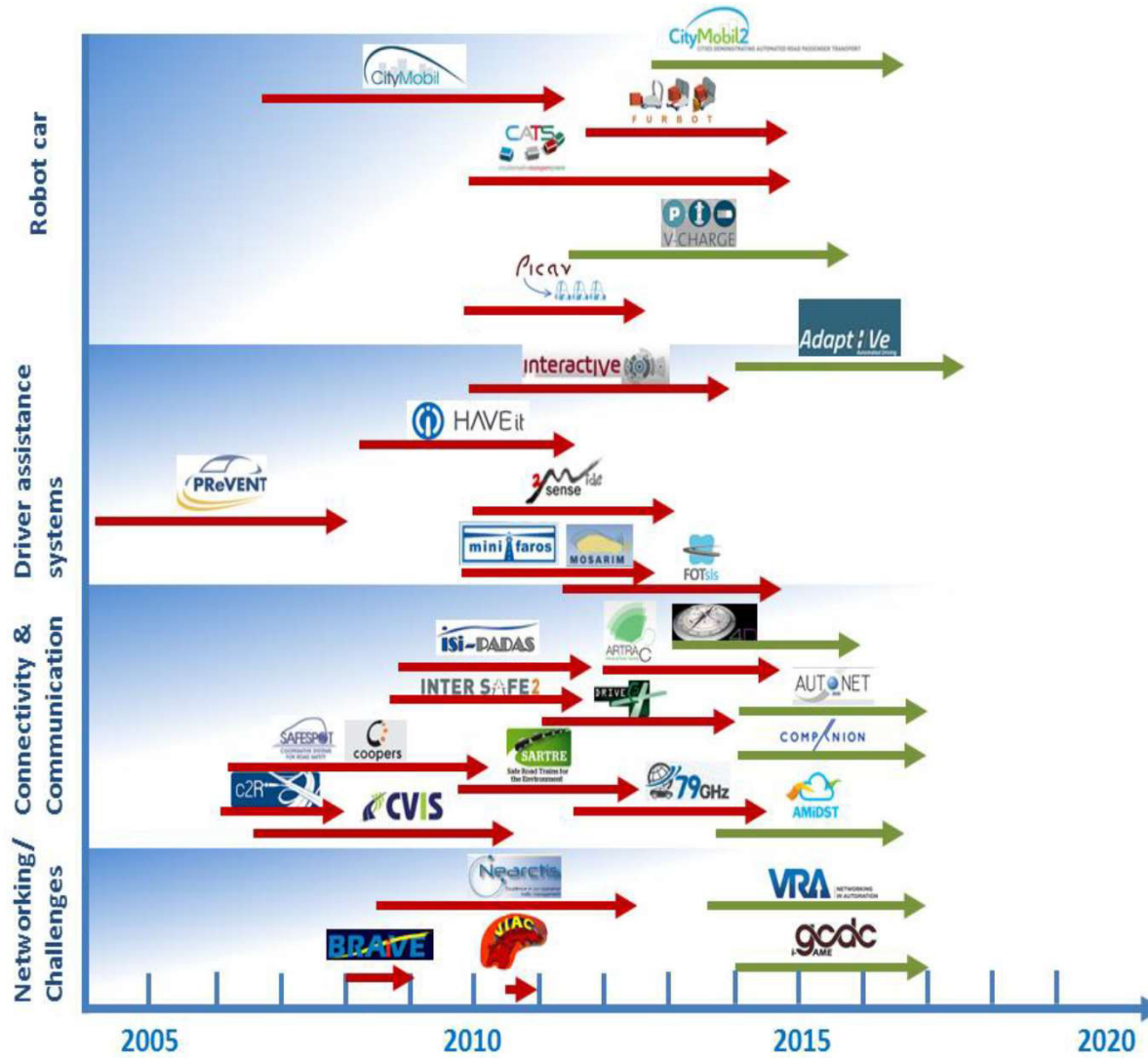


Figure 2: The main automation deployment paths

EPoSS – Roadmap



Copyright: EPoSS

Roadmap III – ECo AT



The C-ITS Corridor NL-DE-AT

Providing a basis for standardized, international, future-oriented cooperative ITS services

- A joint road map for the introduction of the initial cooperative ITS services
- Common functional descriptions of the initial cooperative ITS services and technical specifications
- Start of the actual implementation of the initial cooperative ITS services



Vielen Dank für Ihre Aufmerksamkeit!